

Einführung

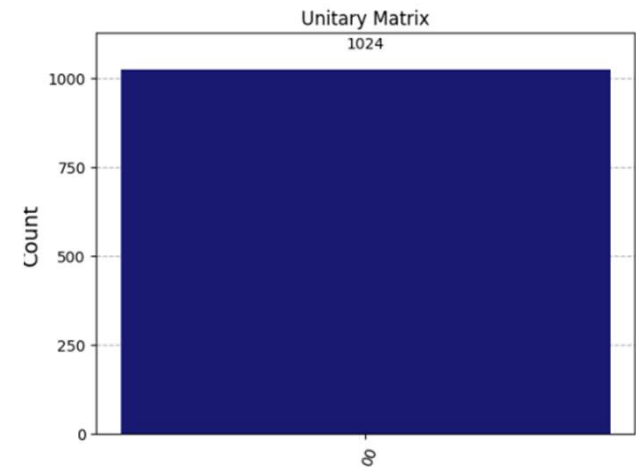
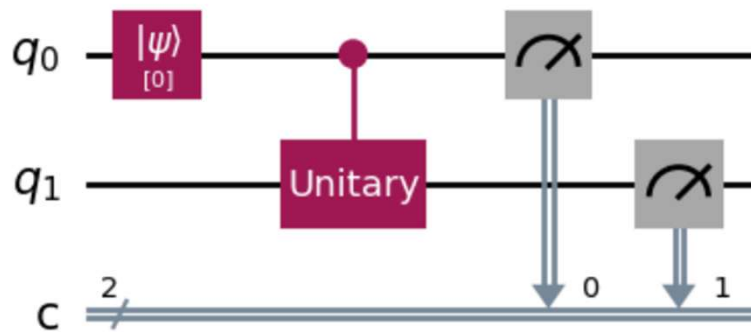
Quantum Computing

HSK 23.10.2024

- **Kontrollierte Gatter**
 - **CNOT**
- **No Cloning Theorem**
- **Deutsch Algorithmus**

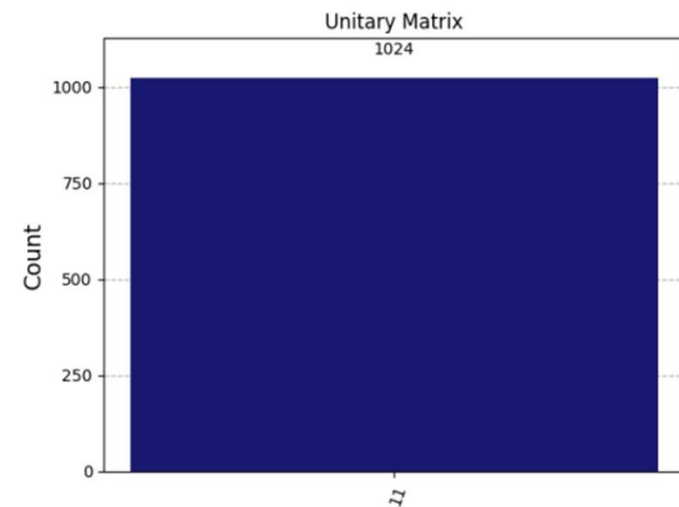
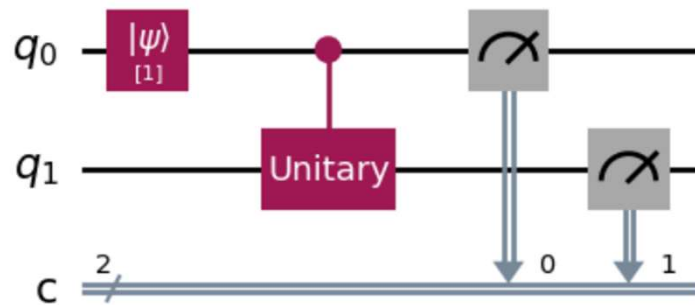
Kontrollierte Unitäre Transformation

$$\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$



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Kontrollierte Unitäre Transformation

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$$\text{CNOT} = \begin{pmatrix} I & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & U \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

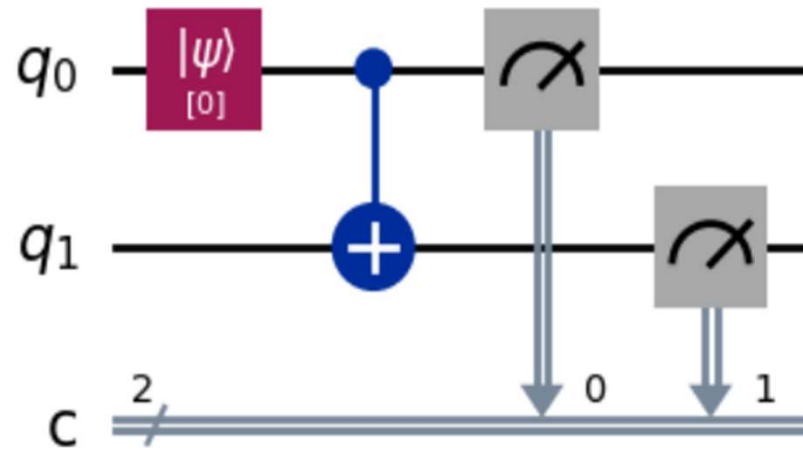
$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

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CNOT Gate



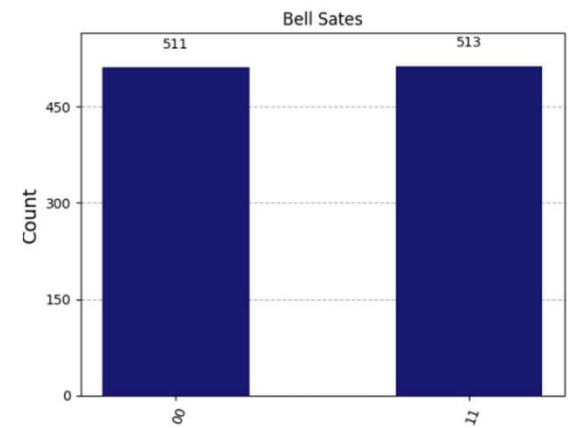
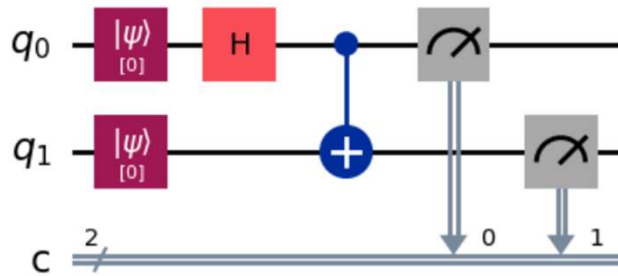
Bell States

$$|\phi^+\rangle = \frac{1}{\sqrt{2}}(|00\rangle + |11\rangle)$$

$$|\phi^-\rangle = \frac{1}{\sqrt{2}}(|00\rangle - |11\rangle)$$

$$|\psi^+\rangle = \frac{1}{\sqrt{2}}(|01\rangle + |10\rangle)$$

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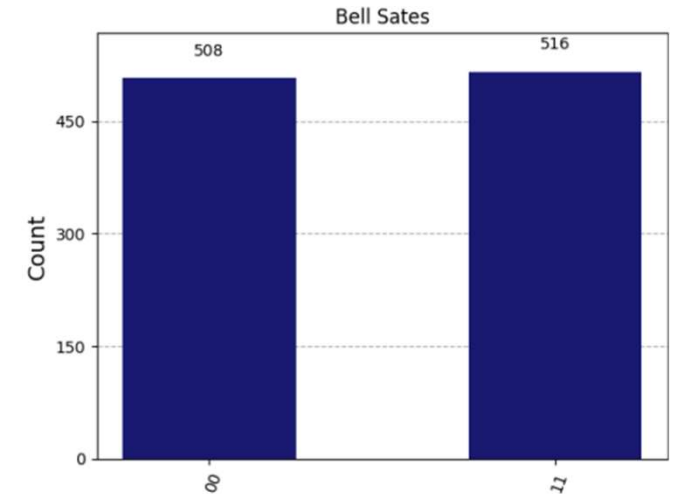
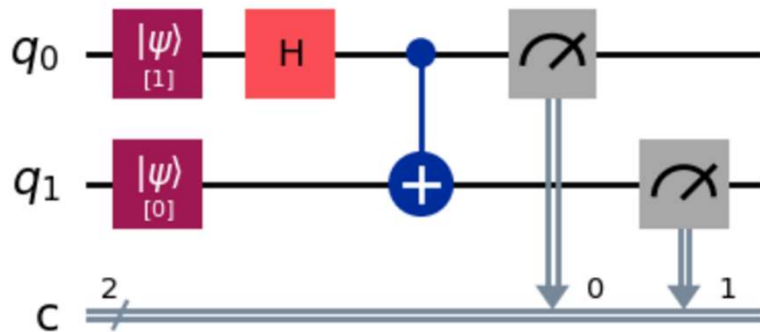
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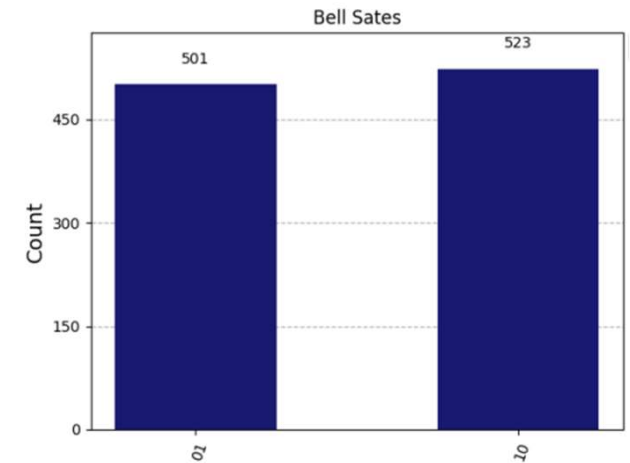
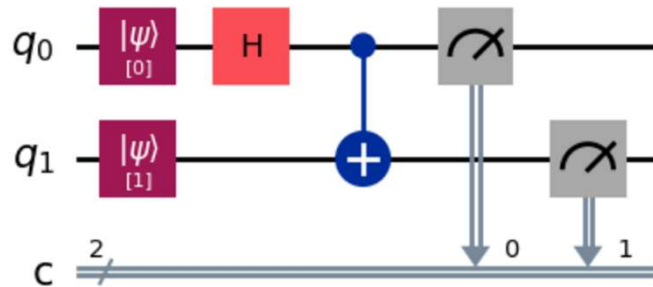
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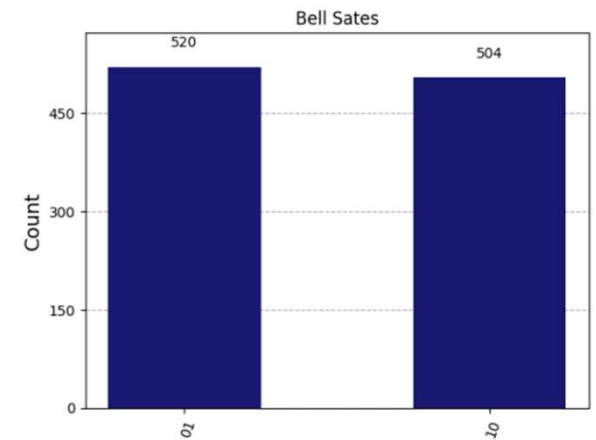
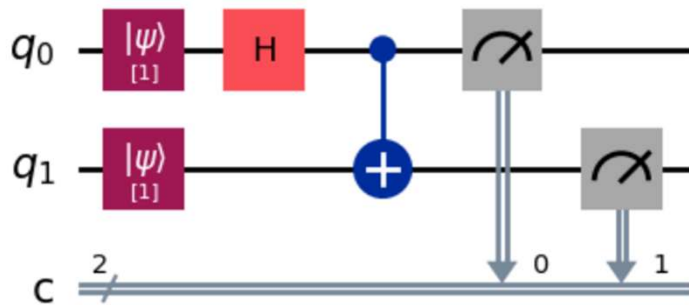
Bell States

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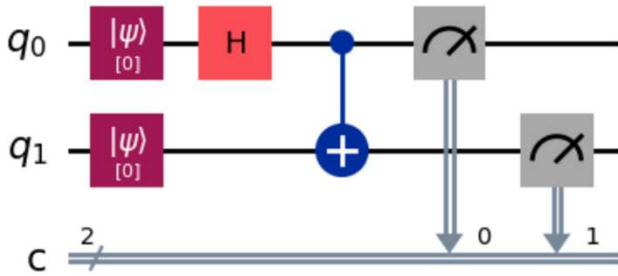
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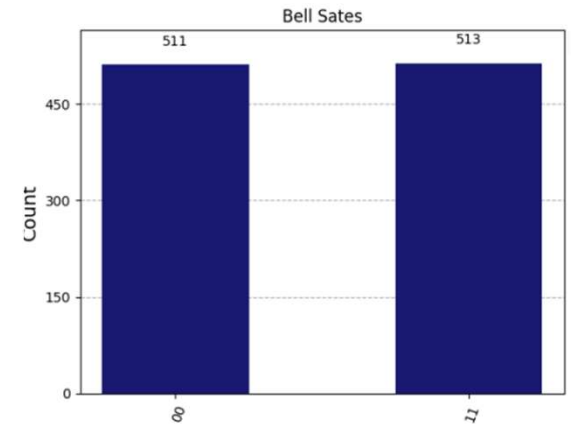
Bell States



$$|\phi^+\rangle = \frac{1}{\sqrt{2}}(|00\rangle + |11\rangle)$$

$$\begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} \otimes \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ 1 \\ \frac{1}{\sqrt{2}} \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ 0 \\ 1 \end{pmatrix} = \frac{1}{\sqrt{2}}(|00\rangle + |11\rangle)$$



No Cloning Theorem

$\exists U, \phi$ so dass $\forall \psi$ gilt $U(|\psi\rangle \otimes |\phi\rangle) = (|\psi\rangle \otimes |\psi\rangle)$

$$|\phi\rangle = |0\rangle$$

$$U(|+\rangle \otimes |0\rangle) = (|+\rangle \otimes |+\rangle) = \frac{1}{2}(|00\rangle + |01\rangle + |10\rangle + |11\rangle)$$

No Cloning Theorem

$$\exists U, \phi \text{ so dass } \forall \psi \text{ gilt } U(|\psi\rangle \otimes |\phi\rangle) = (|\psi\rangle \otimes |\psi\rangle)$$

$$|\phi\rangle = |0\rangle$$

$$U(|+\rangle \otimes |0\rangle) = U\left(\left(\frac{1}{\sqrt{2}}|0\rangle + \frac{1}{\sqrt{2}}|1\rangle\right) \otimes |0\rangle\right) = \frac{1}{\sqrt{2}}U(|0\rangle \otimes |0\rangle) + \frac{1}{\sqrt{2}}U(|1\rangle \otimes |0\rangle)$$

$$U(|0\rangle \otimes |0\rangle) = (|0\rangle \otimes |0\rangle) = |00\rangle$$

$$U(|1\rangle \otimes |0\rangle) = (|1\rangle \otimes |1\rangle) = |11\rangle$$

$$U(|+\rangle \otimes |0\rangle) = \frac{1}{\sqrt{2}}|00\rangle + \frac{1}{\sqrt{2}}|11\rangle$$

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$$U(|+\rangle \otimes |0\rangle) = \frac{1}{\sqrt{2}}|00\rangle + \frac{1}{\sqrt{2}}|11\rangle$$

Deutsch Algorithmus

$$f: \{0,1\} \rightarrow \{0,1\}$$

$$U_f: |xy\rangle \rightarrow |x, y \oplus f(x)\rangle$$

$ xy\rangle$	$f(x) = 0$	$f(x) = 1$	$f(x) = x$	$f(x) = \neg x$
00	00	01	00	01
01	01	00	01	00
10	10	11	11	10
11	11	10	10	11

Deutsch Algorithmus

$$f: \{0,1\} \rightarrow \{0,1\}$$

$$U_f: |xy\rangle \rightarrow |x, y \oplus f(x)\rangle$$

$$f(x) = 0 \quad U_f = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$f(x) = 1 \quad U_f = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

$$f(x) = x \quad U_f = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

$$f(x) = \neg x \quad U_f = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Deutsch Algorithmus

$$f: \{0,1\} \rightarrow \{0,1\}$$

$$U_f: |xy\rangle \rightarrow |x, y \oplus f(x)\rangle$$

$|y\rangle = |0\rangle :$

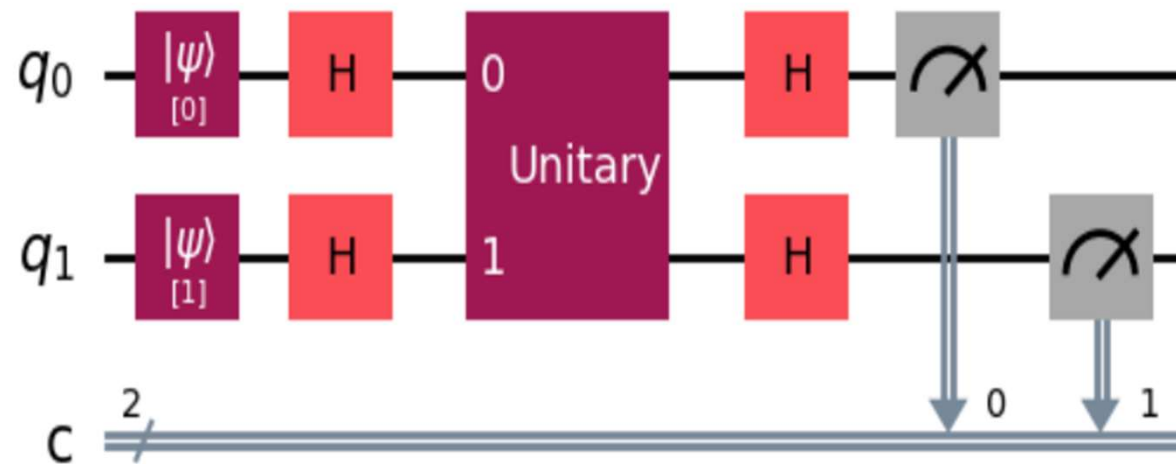
x	U_f	x
$y = 0\rangle$		$f(x)$

$|y\rangle = |-\rangle :$

x	U_f	$(-1)^{f(x)} x\rangle$
$y = -\rangle$		$y = -\rangle$

Deutsch Algorithmus

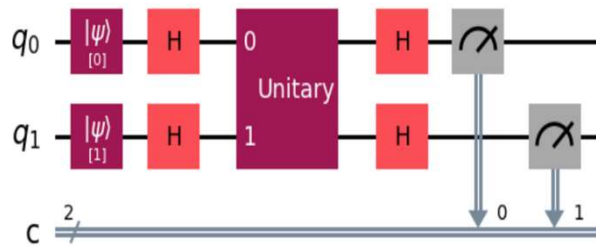
$$U_f: |xy\rangle \rightarrow |x, y \oplus f(x)\rangle$$



Deutsch Algorithmus

$$U_f: |xy\rangle \rightarrow |x, y \oplus f(x)\rangle$$

$$H_2|01\rangle = |+\rangle \cdot |-\rangle$$



$$|f(x)\rangle = -|1 \oplus f(x)\rangle = (-1)^{f(x)} \cdot (|0\rangle - |1\rangle)$$

$$U_f(|+\rangle \cdot |-\rangle) = |+\rangle \cdot (-1)^{f(x)} |-\rangle$$

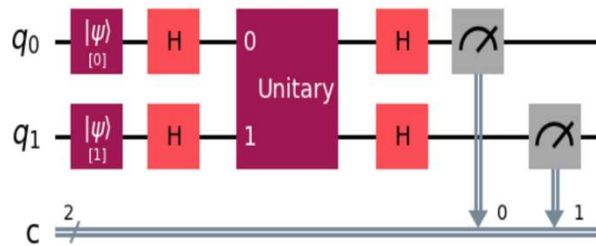
$$U_f(|+\rangle \cdot |-\rangle) = (-1)^{f(x)} |+\rangle \cdot |-\rangle$$

$$U_f(|+\rangle \cdot |-\rangle) = \frac{1}{\sqrt{2}} \left((-1)^{f(0)} |0\rangle + (-1)^{f(1)} |1\rangle \right) \cdot |-\rangle$$

Deutsch Algorithmus

$$U_f: |xy\rangle \rightarrow |x, y \oplus f(x)\rangle$$

$$U_f(|+\rangle \cdot |-\rangle) = \frac{1}{\sqrt{2}} \left((-1)^{f(0)} |0\rangle + (-1)^{f(1)} |1\rangle \right) \cdot |-\rangle$$



$$f(0) = f(1) :$$

$$U_f(|+\rangle \cdot |-\rangle) = \frac{\pm 1}{\sqrt{2}} |+\rangle \cdot |-\rangle$$

$$f(0) \neq f(1) :$$

Phase Kickback

$$U_f(|+\rangle \cdot |-\rangle) = \frac{\pm 1}{\sqrt{2}} |-\rangle \cdot |-\rangle$$